

## Features

- 29.5 dB Gain at 1575 MHz
- GPS, GLONASS, Galileo and Compass
- 1.0 dB NF at 1575 MHz
- Power ON/OFF Function
- **I<sub>DD</sub> = 9.0 mA @ V<sub>CTL</sub> = 3.0 V**

## Description

ASL22N a LNA for GPS, GLONASS, Galileo and Compass in mobile equipment which requires lower current and component count for small PCB area. Power saving function is built in. Low noise performance is kept over the wide range of power enable voltage and DC power supply voltage. It has also a low noise and high linearity over a wide range of frequency up to 6 GHz.

## Typical Performance

(Supply Voltage = +3 V, T<sub>A</sub> = +25 °C, Z<sub>0</sub> = 50 Ω)

| Parameters                       | Units | Typical |
|----------------------------------|-------|---------|
| Testing Frequency                | MHz   | 1575    |
| Gain                             | dB    | 29.5    |
| S11                              | dB    | -16     |
| S22                              | dB    | -15     |
| Output IP3 <sup>1)</sup>         | dBm   | 19      |
| Noise Figure                     | dB    | 1.0     |
| Output P1dB                      | dBm   | 9.5     |
| Supply Current                   | mA    | 9       |
| Supply Voltage                   | V     | +3      |
| Control Current                  | μA    | 400     |
| Control Voltage V <sub>CTL</sub> | V     | +3      |

1) OIP3 is measured with two tones at an output power of -10 dBm/tone separated by 1 MHz.

## Product Specifications\*

| Parameters                                     | Units | Min | Typ  | Max |
|--|-------|-----|------|-----|
| Frequency                                      | MHz   |     | 1575 |     |
| Gain   | dB    |     | 29.5 |     |
| S11  | dB    |     | -16  |     |
| S22  | dB    |     | -15  |     |
| Output IP3                                     | dBm   |     | 19   |     |
| Noise Figure                                   | dB    |     | 1.0  |     |
| Output P1dB                                    | dBm   |     | 9.5  |     |
| Supply Current                                 | mA    |     | 9    |     |
| Supply Voltage                                 | V     |     | 3    |     |
| Control Current                                | μA    |     | 400  |     |
| Control Voltage V <sub>CTL</sub> <sup>1)</sup> | V     |     | +3   |     |

\*100% in-house DC & RF testing is done on packaged products before taping

<sup>1)</sup> 7dB gain variation @ 1.0 < V<sub>CTL</sub> < 3.0

## Absolute Maximum Ratings

| Parameters  | Rating         |
|---|----------------|
| Operating Case Temperature                                | -40 to +85 °C  |
| Storage Temperature                                       | -40 to +150 °C |
| Supply Voltage  | +5 V           |
| Operating Junction Temperature                            | +150 °C        |
| Input RF Power (CW, 50 Ω matched @ 1575MHz) <sup>1)</sup> | +15 dBm        |

1) Please find the max. input power data from [http://www.asb.co.kr/pdf/Maximum\\_Input\\_Power\\_Analysis.pdf](http://www.asb.co.kr/pdf/Maximum_Input_Power_Analysis.pdf)



Package Style: UQFN6

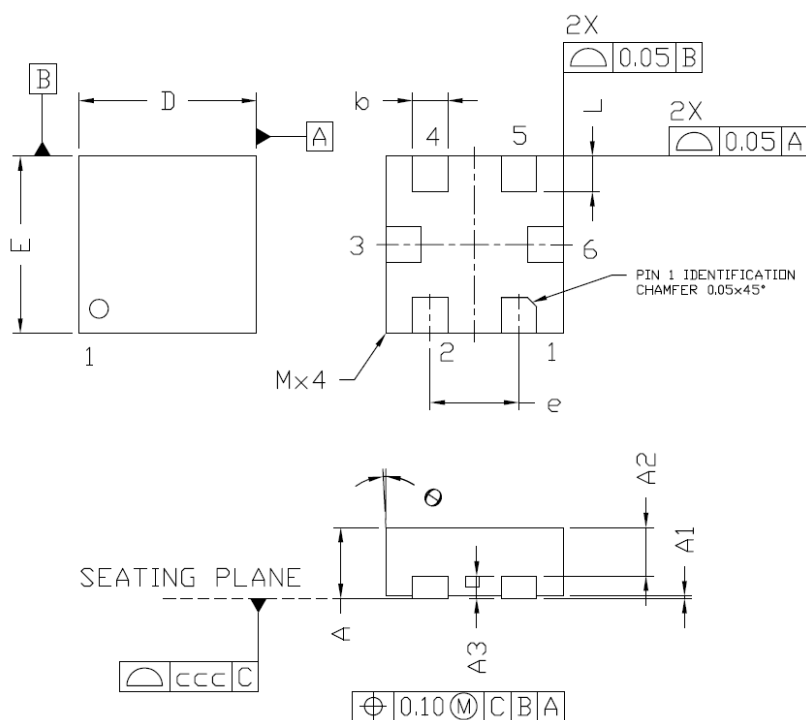
## Applications

- GPS, GLONASS, Galileo, Compass
- 1559 MHz ~ 1610 MHz (3 V)
- 1164 MHz ~ 1300 MHz (3 V)

## Pin Configuration

| Pin No. | Function |
|---------|----------|
| 1       | OUT      |
| 2       | VDD      |
| 3       | GND      |
| 4       | IN       |
| 5       | GND      |
| 6       | VCTL     |

### Outline Drawing



| Symbol   | Dimensions in Millimeters |          |       |
|----------|---------------------------|----------|-------|
|          | MIN                       | NOM      | MAX   |
| A        | 0.35                      | ---      | 0.40  |
| A1       | 0.00                      | ---      | 0.05  |
| A2       | 0.223                     | ---      | 0.273 |
| A3       | ---                       | 0.127REF | ---   |
| b        | 0.15                      | 0.20     | 0.25  |
| D        | 0.95                      | 1.00     | 1.03  |
| E        | 0.95                      | 1.00     | 1.03  |
| e        | ---                       | 0.50BSC  | ---   |
| L        | 0.15                      | 0.20     | 0.25  |
| $\theta$ | -12                       | ---      | 0     |
| ccc      | ---                       | 0.05     | ---   |
| M        | ---                       | ---      | 0.05  |
| Burr     | 0.00                      | 0.03     | 0.06  |

| Pin NO. | Function | Pin NO. | Function. |
|---------|----------|---------|-----------|
| 1       | OUT      | 4       | IN        |
| 2       | VDD      | 5       | GND       |
| 3       | GND      | 6       | VCTL      |

### ESD Classification & Moisture Sensitivity Level

#### ESD Classification

|     |                      |
|-----|----------------------|
| HBM | Class 0              |
|     | Voltage Level: 200 V |
| MM  | Class A              |
|     | Voltage Level: 40 V  |

CAUTION: ESD-sensitive device!

#### Moisture Sensitivity Level (MSL)

Level 3 at 260 °C reflow

### APPLICATION CIRCUIT

GPS, GLONASS, Galileo & Compass

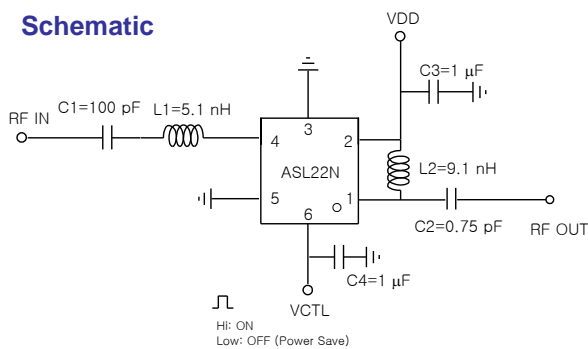
1559 MHz ~ 1610 MHz

+3 V

| Frequency (MHz)                      | 1575 |
|--------------------------------------|------|
| Magnitude S21 (dB)                   | 29.5 |
| Magnitude S11 (dB)                   | -16  |
| Magnitude S22 (dB)                   | -15  |
| Output P1dB (dBm)                    | 9.5  |
| Output IP3 <sup>1)</sup> (dBm)       | 19   |
| Noise Figure (dB)                    | 1.0  |
| Supply Current (mA)                  | 9    |
| Supply Voltage (V)                   | +3   |
| Control Current ( $\mu$ A)           | 400  |
| Control Voltage V <sub>CTL</sub> (V) | +3   |

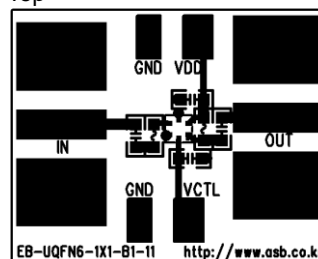
1) OIP3 is measured with two tones at an output power of -10 dBm/tone separated by 1MHz.

### Schematic

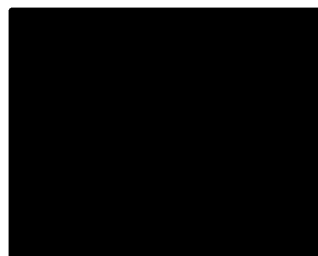


### Board Layout (FR4, 14x11.3 mm<sup>2</sup>, 0.8T)

Top

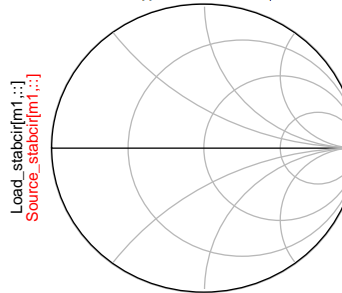
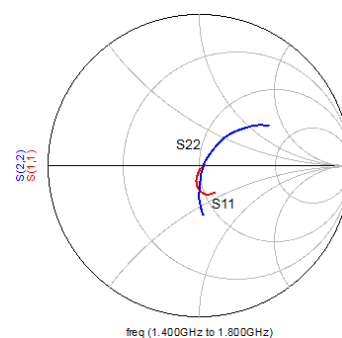
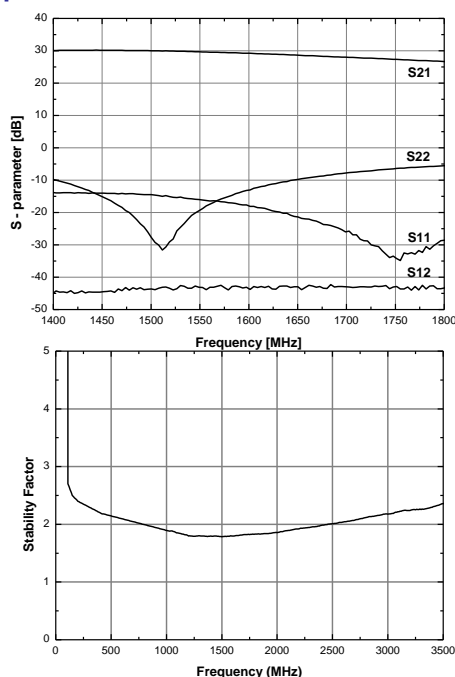


Bottom



\* On this evaluation circuit, C4 does not make any difference, so may not be used. But, using C4 or not shall be decided upon the GPS system board.

### S-parameters



indep(Source\_stabcir[m1,:]) (0.000 to 51.000)  
indep(Load\_stabcir[m1,:]) (0.000 to 51.000)

### APPLICATION CIRCUIT

GPS, GLONASS, Galileo, Compass

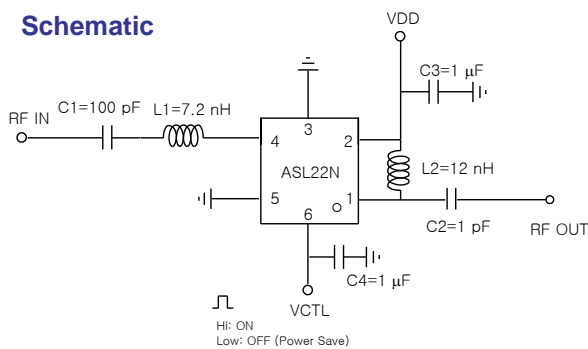
1164 MHz ~ 1300 MHz

+3 V

| Frequency (MHz)                      | 1227 |
|--------------------------------------|------|
| Magnitude S21 (dB)                   | 30   |
| Magnitude S11 (dB)                   | -16  |
| Magnitude S22 (dB)                   | -11  |
| Output P1dB (dBm)                    | 10   |
| Output IP3 <sup>1)</sup> (dBm)       | 18   |
| Noise Figure (dB)                    | 1.05 |
| Supply Current (mA)                  | 9    |
| Supply Voltage (V)                   | +3   |
| Control Current (μA)                 | 400  |
| Control Voltage V <sub>CTL</sub> (V) | +3   |

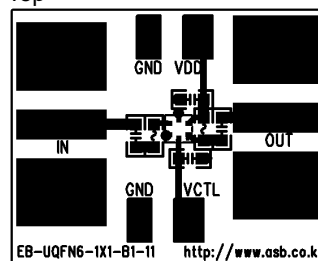
1) OIP3 is measured with two tones at an output power of -10 dBm/tone separated by 1MHz.

### Schematic

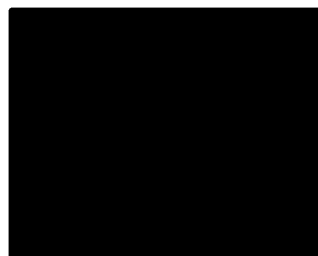


### Board Layout (FR4, 14x11.3 mm<sup>2</sup>, 0.8T)

Top



Bottom



\* On this evaluation circuit, C4 does not make any difference, so may not be used. But, using C4 or not shall be decided upon the GPS system board.

### S-parameters

